


Configurational temperature in active matter. I. Lines of invariant physics in the phase diagram of the Ornstein-Uhlenbeck model

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This paper shows that the configurational temperature of liquid-state theory, T_{conf} , defines an energy scale, which can be used for adjusting model parameters of active Ornstein-Uhlenbeck particle (AOUP) models in order to achieve approximately invariant structure and dynamics upon a density change. The required parameter changes are calculated from the variation of a single configuration's T_{conf} for a uniform scaling of all particle coordinates. The resulting equations are justified theoretically for models involving a potential-energy function with hidden scale invariance. The validity of the procedure is illustrated by computer simulations of the Kob-Andersen binary Lennard-Jones AOUP model, showing the existence of lines of approximate invariance of the reduced-unit radial distribution function and time-dependent mean-square displacement.

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I. INTRODUCTION

Any system in thermal equilibrium has a well-defined temperature, and the temperature concept is fundamental for understanding and quantifying a system's thermodynamic and statistical-mechanical properties. In view of this it is obvious to try to generalize temperature to characterize also nonequilibrium systems. Excellent reviews of such proposed temperatures are given in Refs. [1–5]. Examples are the *effective temperature* quantifying deviations from the fluctuation-dissipation theorem [6–8] and the *fictive temperature* characterizing a glass's structure in terms of the temperature at which the liquid solidified [9,10]. Nonequilibrium temperatures are generally motivated by the prospect of connecting properties of the nonequilibrium system to those of the same system in thermal equilibrium. That is not the background, however, of the below proposed application of liquid-state theory's *configurational temperature* [2,11–13] to active-matter models.

Active matter is an umbrella term used to describe physical systems whose building blocks can autonomously perform mechanical work. This includes fluids consisting of self-propelled particles, e.g., suspensions of swimming bacteria or animal groups, mutually propelled particles like cytoskeletal filaments or motor proteins, cells in various contexts, bird or insect flock dynamics, etc. [14–21]. Active matter is usually not time reversible. This means that a multitude of different dynamics may come into play [22], making this a much richer field of study than that of ordinary time-reversible dynamics [23]. A noted feature of active matter is motility-induced phase separation (MIPS), the intriguing finding that even a purely repulsive system may phase separate into high- and low-density phases [17,19,24–28].

Active matter does not have states of ordinary thermal equilibrium, but there have been suggestions for mapping active-matter states to equilibrium, implying the existence of an active-matter temperature. For instance, Szamel proposed an effective temperature for a single self-propelled particle [29], and Fodor *et al.* showed [30] that for active Ornstein-Uhlenbeck particles with a small persistence time one can identify an effective temperature from the analog of the fluctuation-dissipation theorem (see also Refs. [31–33]). In a parallel development, Takatori and Brady formulated a thermodynamic-type temperature for active matter based on the swim-pressure concept [34].

For an ordinary nonactive system in thermal equilibrium, the temperature T equals T_{conf} defined as follows [2,12]. For a system of N particles with collective coordinate vector $\mathbf{R} \equiv (\mathbf{r}_1, \dots, \mathbf{r}_N)$ and potential-energy function $U(\mathbf{R})$, $k_B T_{\text{conf}} \equiv \langle (\nabla U)^2 \rangle / \langle \nabla^2 U \rangle$ in which k_B is the Boltzmann constant, ∇ is the gradient operator in the $3N$ -dimensional configuration space, and the sharp brackets denote canonical-ensemble averages. The proof that $T_{\text{conf}} = T$ in equilibrium is so simple that it deserves to be repeated here [11]: If Z is the configuration-space partition function integral, a partial integration of $\langle \nabla^2 U \rangle = \int \nabla^2 U(\mathbf{R}) \exp[-U(\mathbf{R})/k_B T] d\mathbf{R} / Z$ leads to $\langle \nabla^2 U \rangle = - \int \nabla U(\mathbf{R}) \cdot \nabla \exp[-U(\mathbf{R})/k_B T] d\mathbf{R} / Z = \langle (\nabla U)^2 \rangle / k_B T$ from which $T_{\text{conf}} = T$ follows.

Approaching the thermodynamic limit, the relative fluctuations of both the numerator and the denominator of T_{conf} vanish. This means that if one defines an \mathbf{R} -dependent configurational temperature by

$$k_B T_{\text{conf}}(\mathbf{R}) \equiv \frac{[\nabla U(\mathbf{R})]^2}{\nabla^2 U(\mathbf{R})}, \quad (1)$$

the identity $T_{\text{conf}}(\mathbf{R}) \cong T$ applies in the sense that deviations go to zero as $N \rightarrow \infty$. We have this limit in mind throughout and shall (mostly) ignore that $T_{\text{conf}}(\mathbf{R})$ fluctuates for any finite system. Note that the configurational temperature is not defined for a system of free particles. Note also that configurations with $\nabla^2 U(\mathbf{R}) = 0$ become less likely as $N \rightarrow \infty$, so

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the fact that Eq. (1) is not defined for such configurations is irrelevant; by the same reasoning one can ignore the existence of configurations for which $\nabla^2 U(\mathbf{R}) < 0$. We return briefly to a discussion of T_{conf} fluctuations in simulations (Sec. II).

Since the derivation of the configurational temperature T_{conf} is based on the fact that the probability in the canonical ensemble of configuration \mathbf{R} is proportional to $\exp[-U(\mathbf{R})/k_B T]$, it would appear that T_{conf} cannot be relevant for systems that are far from thermal equilibrium. We show in this paper, however, that $T_{\text{conf}}(\mathbf{R})$ may be used for tracing out lines of invariant structure and dynamics in the phase diagram of active-matter models with hidden scale invariance. This is the symmetry that the ordering of configurations according to their potential energy at a given density is maintained if these are scaled uniformly to a different density [Eq. (6) below], a property that applies to a good approximation for the liquid and solid phases of a number of well-known potentials, including the Lennard-Jones and Yukawa pair potentials [35–38], as well as for more complicated nonpair interactions [39–41]. The companion paper (Paper II) [42] presents a different application of T_{conf} to active matter by proposing that the ratio of the so-called systemic temperature [43] to T_{conf} quantifies the deviation from ordinary thermal equilibrium. Both papers focus on active-matter models without orientational interactions, i.e., models based on point particles.

II. LINES OF APPROXIMATELY INVARIANT PHYSICS IN THE PHASE DIAGRAM OF THE KOB-ANDERSEN AOUP MODEL

This section studies active Ornstein-Uhlenbeck particle (AOUP) dynamics, which has no momentum conservation and for which hydrodynamics is not taken into account. All information about the particle interactions is contained in the potential-energy function $U(\mathbf{R})$ [15,20,44]. In configuration space the AOUP equation of motion [30,45–47] is

$$\dot{\mathbf{R}} = \mu \mathbf{F}(\mathbf{R}) + \boldsymbol{\eta}(t). \quad (2)$$

Here μ is the mobility (velocity over force) and the force vector is given by $\mathbf{F}(\mathbf{R}) = -\nabla U(\mathbf{R})$. The noise vector $\boldsymbol{\eta}(t)$ is colored according to an Ornstein-Uhlenbeck process, i.e., is a Gaussian stochastic process characterized by

$$\langle \eta_i^\alpha(t) \eta_j^\beta(t') \rangle = \delta_{ij} \delta_{\alpha\beta} \frac{D}{\tau} e^{-|t-t'|/\tau} \quad (3)$$

in which i and j are particle indices, α and β are spatial xyz indices, and D and τ are constants. We are interested in how the physics is affected if the density is changed, in particular whether approximately invariant physics can be obtained by adjusting D and τ (regarding μ as a system-specific constant).

The dimension of μ is length squared over energy times time. Thus, if l_0 is a length unit, t_0 a time unit, and e_0 an energy unit, the quantity $\mu t_0 e_0 / l_0^2$ is dimensionless. Likewise, $D t_0 / l_0^2$ and τ / t_0 are dimensionless because D has dimension of a diffusion coefficient and τ of a time. It is reasonable to expect that when the density is changed, invariant physics can come about only if these three dimensionless quantities do not change—although this criterion of course depends on the choice of units. As length unit we take the average

interparticle spacing, $l_0 = \rho^{-1/3}$ (working in 3 dimensions). The colored-noise correlation time τ of Eq. (3) is a natural choice for the time unit, $t_0 = \tau$. The idea is now to investigate the consequences of using for the energy unit the configurational temperature, i.e., of choosing $e_0 = k_B T_{\text{conf}}$ (Sec. III justifies this choice). If the above two dimensionless quantities are to be invariant when density varies, the following must apply: $\mu \propto l_0^2 / (t_0 e_0) = \rho^{-2/3} / (\tau k_B T_{\text{conf}})$ and $D \propto l_0^2 / t_0 = \rho^{-2/3} / \tau$. Since μ is taken to be constant, this leads to $\tau \propto \rho^{-2/3} / \mu k_B T_{\text{conf}}$ and $D \propto \mu k_B T_{\text{conf}}$. Thus the following equations determine D and τ at density ρ from their values D_0 and τ_0 at a reference state point of density ρ_0 ,

$$D = D_0 \frac{T_{\text{conf}}(\rho)}{T_{\text{conf}}(\rho_0)}, \quad \tau = \tau_0 \left(\frac{\rho_0}{\rho} \right)^{2/3} \frac{T_{\text{conf}}(\rho_0)}{T_{\text{conf}}(\rho)}. \quad (4)$$

We note that D is proportional to the configurational temperature $T_{\text{conf}}(\rho)$, a finding that is analogous to the equilibrium result $D \propto T$ in which T is the temperature [see the next paragraph for the definition of $T_{\text{conf}}(\rho)$].

As mentioned, fluctuations are small for a large system, and in that case $T_{\text{conf}}(\rho_0)$ may be evaluated reliably from a single configuration of a steady-state simulation, \mathbf{R}_0 : $T_{\text{conf}}(\rho_0) \cong T_{\text{conf}}(\mathbf{R}_0)$. In order to find $T_{\text{conf}}(\rho)$ one scales \mathbf{R}_0 uniformly to the density ρ using $\mathbf{R} = (\rho_0/\rho)^{1/3} \mathbf{R}_0$; the configurational temperature of Eq. (4) is then identified from $T_{\text{conf}}(\rho) \cong T_{\text{conf}}(\mathbf{R})$. This leads to the following recipe for calculating D and τ at density ρ :

$$D = D_0 \frac{T_{\text{conf}}[(\rho_0/\rho)^{1/3} \mathbf{R}_0]}{T_{\text{conf}}(\mathbf{R}_0)}, \quad \tau = \tau_0 \left(\frac{\rho_0}{\rho} \right)^{2/3} \frac{T_{\text{conf}}(\mathbf{R}_0)}{T_{\text{conf}}[(\rho_0/\rho)^{1/3} \mathbf{R}_0]}. \quad (5)$$

To test the predicted invariance of structure and dynamics in reduced units when parameters vary with density according to Eq. (5), we simulated the AOUP Kob-Andersen (KA) binary Lennard-Jones (LJ) model in three dimensions [48]. A KA system of 10 000 particles consisting of the standard mix of two types of LJ particles, A (80%) and B (20%), was studied. Writing the LJ pair potential between particles of type α and β as $v_{\alpha\beta}(r) = 4\varepsilon_{\alpha\beta}[(r/\sigma_{\alpha\beta})^{-12} - (r/\sigma_{\alpha\beta})^{-6}]$ with $\alpha, \beta = A$ or B , the KA parameters are [48] $\sigma_{AA} = 1.0$, $\sigma_{AB} = \sigma_{BA} = 0.8$, $\sigma_{BB} = 0.88$, $\varepsilon_{AA} = 1.0$, $\varepsilon_{AB} = \varepsilon_{BA} = 1.5$, $\varepsilon_{BB} = 0.5$. A shifted-force cutoff of $v_{\alpha\beta}(r)$ at $r_{\text{cut}} = 2.5\sigma_{\alpha\beta}$ was used [49]. The simulations employed the time step $\Delta t = \Delta \tilde{t} / (D \rho^{2/3})$ in which $\Delta \tilde{t} = 0.4$. At the reference state-point density, $\rho_0 = 1.2$, $\Delta t = 0.0001$ was used. The

TABLE I. Density ρ and model parameters D and τ along the predicted line of invariance calculated from Eq. (5) in which $T_{\text{conf}}(\rho)$ is determined from a single configuration \mathbf{R}_0 by means of Eq. (1) after a uniform scaling to density ρ .

ρ	D	τ	T_{conf}
1.2	3000	10.000	0.2742
1.5	9859	2.622	0.9014
2.0	39 160	0.5450	3.580
2.5	105 600	0.1741	9.657
3.0	230 800	0.0706	21.10

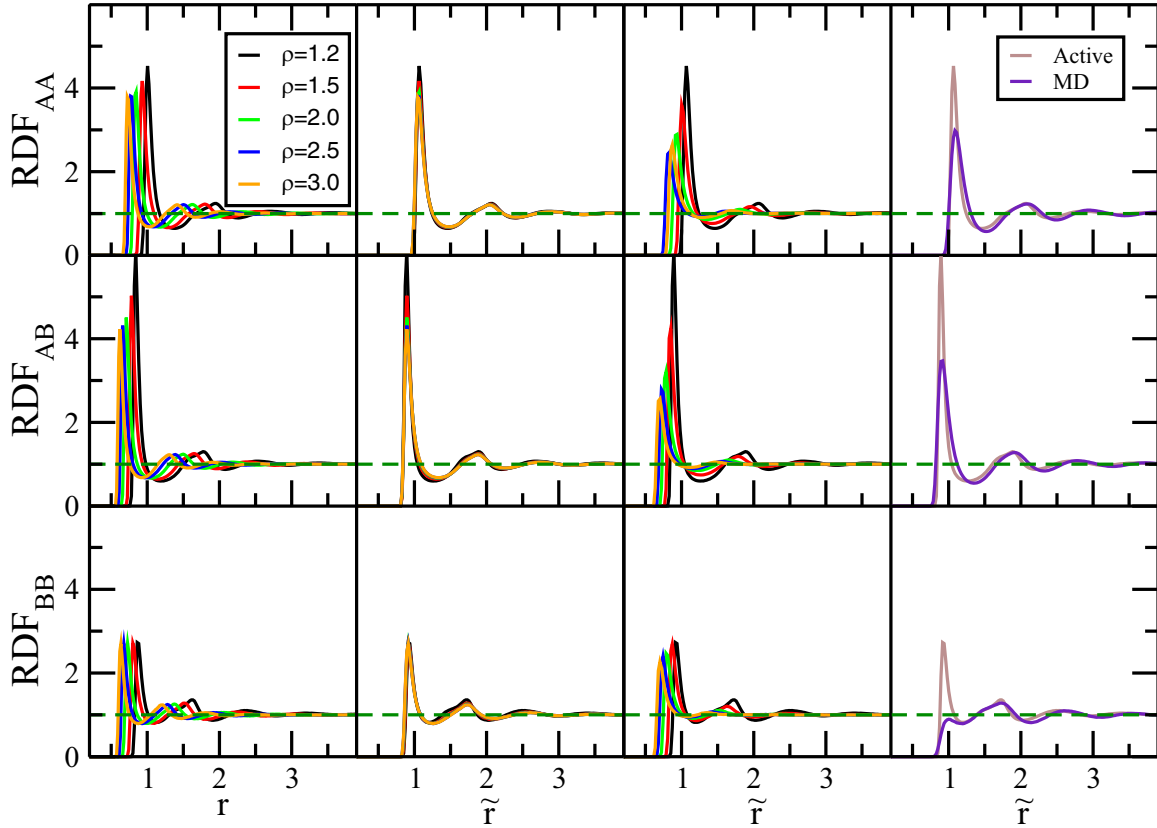


FIG. 1. Radial distribution functions (RDF) of the Kob-Andersen system with AOUP dynamics at densities between 1.2 and 3.0 for the model parameters D and τ of Table I determined by means of Eq. (1) and Eq. (5), as described in the text. The first column shows the three partial RDFs along the proposed line of invariance, which is generated from a single configuration of the reference state point $(\rho_0, D_0, \tau_0) = (1.2, 3000, 10)$, plotted as functions of the pair distance r . The second column shows the same data as functions of the reduced pair distance $\tilde{r} \equiv \rho^{1/3}r$, revealing a good collapse except at the first peak. For comparison, the third column shows data for the same values of D and τ as the two previous columns but at density $\rho = 1.2$, while the fourth column shows AOUP data at the reference state point (brown) and standard molecular dynamics (MD) thermal equilibrium data at the density $\rho = 1.2$ (indigo) evaluated at the MD temperature resulting in the same average potential energy as that of the AOUP simulation, $T = 1.57$ (this is the AOUP system's so-called systemic temperature [43]).

simulations were carried out on GPU cards; active-matter simulations used a home-made code while MD simulations used the Roskilde University Molecular Dynamics (RUMD) package [50].

Table I reports the resulting values of D and τ for densities ranging from 1.2 to 3.0, starting from the reference state point $(\rho, D, \tau) = (1.2, 3000, 10)$. In the two left columns of Fig. 1 the three partial radial distribution functions (RDFs) along the predicted line of invariance are shown as a function of the radial distance r and the reduced radial distance $\tilde{r} \equiv \rho^{1/3}r$, respectively. The latter shows good invariance, except that the height of the first peak is not invariant, in particular for RDF_{AB} . The third column of Fig. 1 shows the results for the same values of D and τ as previously (Table I), but at the reference-state-point density $\rho = 1.2$, in which case no invariance is observed. The fourth column compares the reference density RDFs with those of an equilibrium molecular dynamics (MD) simulation at the reference density and the temperature at which the average potential energy is equal to that of the reference-state-point AOUP simulation ($T = 1.57$), showing little resemblance. Incidentally, this “systemic” temperature [43] is quite different from the configurational temperature, $T_{\text{conf}} = 0.27$, which corresponds

to a such a deeply supercooled state for the Newtonian system that the metastable liquid cannot be equilibrated using state-of-the-art MD.

Figure 2 shows the mean-square displacement (MSD) of the A and B particles as functions of time. The four columns are similar to those of Fig. 1 with the time t as the abscissa in the first column and the reduced time $\tilde{t} \equiv (D\rho^{2/3})t \propto t/\tau$ in the second, where the MSD is also given in reduced units, i.e., multiplied by $\rho^{2/3}$. The latter shows approximate invariance of the dynamics.

It is instructive to consider the limits of short and long times. For $t \rightarrow 0$, i.e., in the “ballistic” regime, Eq. (2) and Eq. (3) imply that the MSD is proportional to $(D/\tau)t^2$, while for $t \rightarrow \infty$ the MSD is proportional to Dt . Thus the reduced-unit short- and long-time limit MSDs are proportional to $\rho^{2/3}D\tau\tilde{t}^2$ and $\rho^{2/3}D\tau\tilde{t}$, respectively. Since Eq. (5) implies that $\rho^{2/3}D\tau$ is a constant, this means that in these limit the MSDs are proportional to \tilde{t}^2 and \tilde{t} , respectively. This is confirmed by the second column of Fig. 2. The third column of Fig. 2 gives the reduced MSD using the predicted D and τ at the reference density. The fourth column compares the reference state point MSDs to those of $T = 1.57$ MD simulation. We conclude from Fig. 1 and Fig. 2 that there is

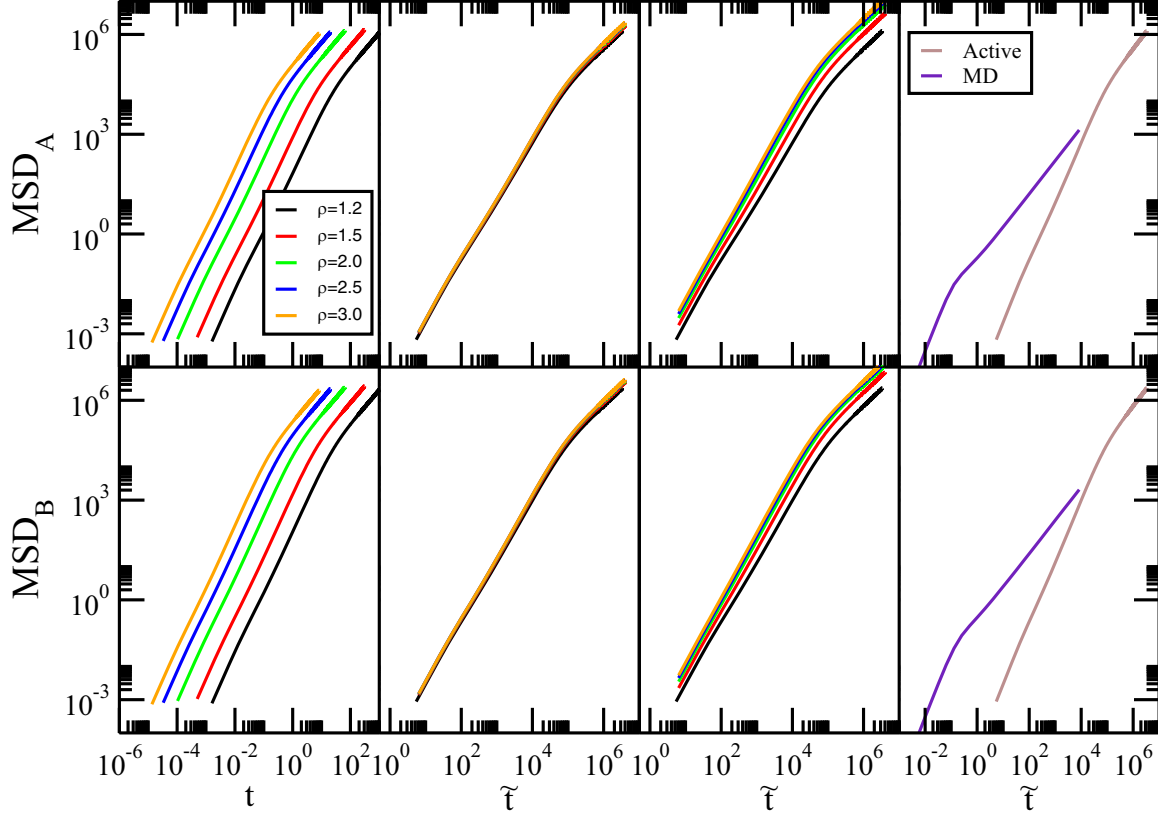


FIG. 2. Mean-square displacement (MSD) at the same state points as in Fig. 1. The first column shows the MSDs of the A and B particles along the predicted line of invariance, plotted as functions of the time t . The second column shows the same data in reduced units (defined in the text), revealing a good collapse. The third column shows reduced data for the same values of D and τ as the previous figures but at the density $\rho = 1.2$. The fourth column shows a comparison of the reduced MSD AOUP data at the reference state point (brown) to the standard reduced MD thermal-equilibrium MSD (indigo) at $\rho = 1.2$, where the temperature as in Fig. 1 was determined to result in the same average potential energy as that of the AOUP simulation, leading to $T_{MD} = 1.57$.

an approximate invariance of the reduced-unit structure and dynamics.

Figure 3 investigates the robustness of the procedure. Figure 3(a) shows T_{conf} as a function of ρ in a log-log plot for the selected scaling configuration \mathbf{R}_0 used in Eq. (5). The curve slope reveals that at high density one finds almost $T_{\text{conf}}(\rho) \propto \rho^4$, reflecting the dominance here of the r^{-12} repulsive term of the LJ pair potential [it follows from Eq. (1) that $T_{\text{conf}}(\rho) \propto \rho^{n/3}$ for a system of r^{-n} inverse power-law pair potentials]. At lower densities this does not apply, however, demonstrating that the invariance of structure and dynamics is not simply a consequence of the scale-invariant repulsive r^{-12} term of the LJ pair potential. Figure 3(b) shows the distribution of configurational temperatures at the reference state point. We find a fairly broad distribution, which motivated an investigation into how much the prediction of the invariance line depends on the choice of \mathbf{R}_0 . Figures 3(c) and 3(d) show the predictions for D and τ using three different configurations in Eq. (1). The red curve is for the configuration \mathbf{R}_0 used above that was selected from the center of the distribution in Fig. 3(b), the black and blue curves are for two configurations taken from the lower and higher ends of the distribution, respectively. For both D and τ there is little visible difference, and we indeed find that the RDFs and MSDs are virtually

indistinguishable from those of Fig. 1 and Fig. 2 (data not shown). Only a ratio of configurational temperatures appears in Eq. (5), and these data suggest that a significant cancellation occurs. We conclude that, despite a relatively large spread of configurational temperatures, 10 000 particles are enough for Eq. (4) to be used for predicting model parameters resulting in approximately invariant structure and dynamics.

III. THEORETICAL JUSTIFICATION OF THE PROCEDURE

How can the characteristic energy $k_B T_{\text{conf}}$ of the canonical ensemble be relevant for identifying lines of invariant physics for an active-matter system? While the energy $k_B T_{\text{conf}}$ *per se* is hardly important, we argue below that the *ratio* $T_{\text{conf}}(\rho)/T_{\text{conf}}(\rho_0)$ determines the *ratio* of the relevant energy scales at the two densities in question. To arrive at this conclusion, we first summarize relevant aspects of the isomorph theory.

The starting point is that the KA model to a good approximation obeys the hidden-scale-invariance uniform-scaling symmetry defined [36,38] by the following logical implication for the potential-energy function $U(\mathbf{R})$,

$$U(\mathbf{R}_a) < U(\mathbf{R}_b) \Rightarrow U(\lambda \mathbf{R}_a) < U(\lambda \mathbf{R}_b). \quad (6)$$

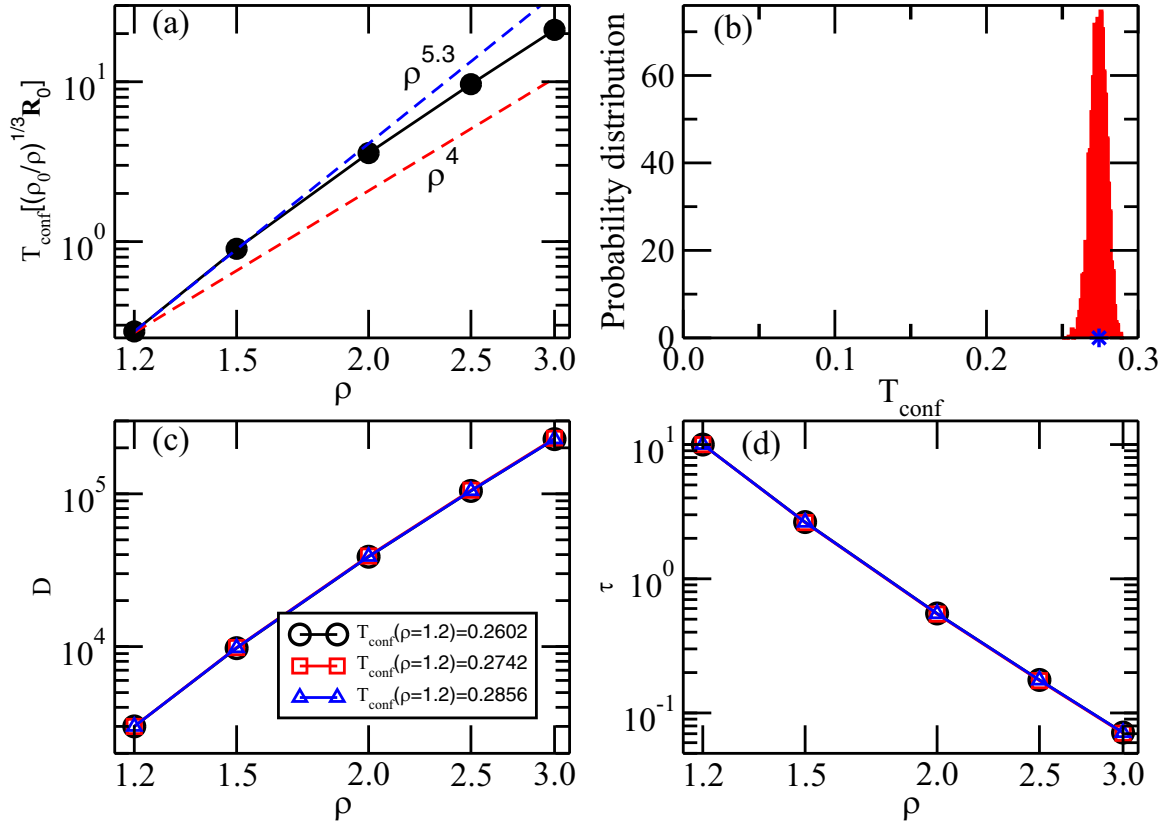


FIG. 3. Variation of T_{conf} , D , and τ . (a) The configurational temperature T_{conf} as a function of the density for the scaling configuration, \mathbf{R}_0 . At the highest densities, T_{conf} is almost proportional to ρ^4 (red dashed line); this is where the repulsive r^{-12} term of the LJ pair potential dominates the potential energy. At the lowest densities, the scaling is approximately proportional to $\rho^{5.3}$ (blue dashed line), showing that the scaling is nontrivial. (b) The distribution of $T_{\text{conf}}(\mathbf{R})$ for several configurations at the reference state point for a system of 10 000 particles. The spread is larger than expected from a simple statistical $1/\sqrt{N}$ argument. The blue star marks T_{conf} of the reference scaling configuration \mathbf{R}_0 . (c) How D varies according to Eq. (5) for three different configurations: one is the \mathbf{R}_0 used in Fig. 1 and Fig. 2 from the center of the distribution in (b) (red), the two others are from the lowest and highest ends of the distribution (black and blue). (d) How τ varies according to Eq. (5) for the same three configurations. No significant differences are seen for the predicted parameters, meaning that 10 000 particles are enough for using a single configuration to determine how to scale the AOUP model parameters.

Here \mathbf{R}_a and \mathbf{R}_b are configurations of same density and λ is a scaling parameter. Physically, Eq. (6) expresses that the ordering of configurations at one density according to their potential energy is maintained when scaled uniformly to a different density.

Recall that at a given thermodynamic equilibrium state point, the excess entropy S_{ex} is defined as the entropy minus the ideal-gas entropy at the same density and temperature [51]. In the case of ordinary Newtonian mechanics, Eq. (6) implies that structure and dynamics in reduced units (defined below) are invariant along the curves of constant excess entropy [35,36,38]. Such curves are termed isomorphs, and systems with isomorphs are termed R-simple.

Isomorph invariance is exact whenever Eq. (6) applies without exception, but this is never the case for potentials with both attractions and repulsions. Isomorph invariance is still a good approximation, however, if Eq. (6) applies for most of the physically relevant configurations at the state points in question. Depending of course on how far the scaling parameter λ is from unity, this is the case for the majority of metals and van der Waals bonded systems, whereas systems with strong directional interactions like hydrogen-bonded

and covalently bonded systems generally do not conform to Eq. (6) and therefore violate isomorph-theory predictions [52] (ionic and dipolar systems constitute an interesting class in-between). Realistic R-simple pair-potential models include the standard Lennard-Jones model in single-component, binary, and polydisperse versions, as well as with exponents other than 6 and 12 (the so-called Mie potentials), the Yukawa (screened Coulomb) pair potential [36,53], the EXP pair potential [54,55], effective-medium potentials describing metals [41], etc. We emphasize that Eq. (6) and its consequences are not limited to pair-potential systems. For systems with inverse-power-law interactions, the isomorph theory is exact.

For R-simple systems with Newtonian dynamics, the structure and dynamics of the condensed liquid and solid phases are isomorph invariant to a good approximation when made dimensionless using as units the length l_0 , energy e_0 , and time t_0 given by (in which m is the particle mass)

$$l_0 = \rho^{-1/3}, \quad e_0 = k_B T, \quad t_0 = \rho^{-1/3} \sqrt{m/k_B T}. \quad (7)$$

Using this unit system defines the reduced-unit value of the quantity in question (henceforth marked by a tilde).

The microscopic excess-entropy function is defined [36] by $S_{\text{ex}}(\mathbf{R}) \equiv S_{\text{ex}}(\rho, U(\mathbf{R}))$ in which $S_{\text{ex}}(\rho, U)$ is the thermodynamic excess entropy of the equilibrium state point with density ρ and average potential energy U . Note that the function $S_{\text{ex}}(\mathbf{R})$ is defined for any configuration of any system, whether it is R-simple or not. It can be shown that whenever Eq. (6) applies, $S_{\text{ex}}(\mathbf{R})$ depends only on the configuration's reduced coordinates, $\tilde{\mathbf{R}} \equiv \rho^{1/3}\mathbf{R}$ [36]. Thus inverting the relation $S_{\text{ex}}(\mathbf{R}) = S_{\text{ex}}(\rho, U(\mathbf{R}))$ leads for an R-simple system to

$$U(\mathbf{R}) = U(\rho, S_{\text{ex}})|_{S_{\text{ex}}=S_{\text{ex}}(\tilde{\mathbf{R}})}, \quad (8)$$

where $U(\rho, S_{\text{ex}})$ is the average potential energy of the thermodynamic equilibrium state point with density ρ and excess entropy S_{ex} . For brevity, the right-hand side of Eq. (8) is usually written as $U(\rho, S_{\text{ex}}(\tilde{\mathbf{R}}))$.

The consequences of Eq. (8) have so far been worked out only for systems with standard time-reversible Newtonian dynamics [36,38]. However, Eq. (8) follows from Eq. (6) that has no reference to thermal equilibrium; hence Eq. (8) may also be applied to active-matter models with a hidden-scale-invariant potential-energy function. Note that the function $S_{\text{ex}}(\mathbf{R})$ still refers to the standard microcanonical ensemble according to which $S_{\text{ex}}(\mathbf{R})$ is basically the logarithm of the number of configurations at the same density with the same potential energy as \mathbf{R} [36].

We proceed to rewrite the AOUP equation of motion in terms of reduced variables. Writing $\mathbf{R} = l_0\tilde{\mathbf{R}}$ and $t = t_0\tilde{t}$ in which $l_0 = \rho^{-1/3}$ and $t_0 = \tau$ as in Sec. II, Eq. (2) becomes (with $\tilde{\nabla} = \rho^{-1/3}\nabla$)

$$\frac{l_0}{\tau} \dot{\tilde{\mathbf{R}}} = -\mu \frac{1}{l_0} \tilde{\nabla} U(\mathbf{R}) + \eta(\tilde{t}). \quad (9)$$

The reduced noise is given by $\tilde{\eta} = (\tau/l_0)\eta$ in terms of which Eq. (3) becomes

$$\langle \tilde{\eta}_i^\alpha(\tilde{t}) \tilde{\eta}_j^\beta(\tilde{t}') \rangle = \delta_{ij} \delta_{\alpha\beta} \frac{\tau D}{l_0^2} e^{-|\tilde{t}-\tilde{t}'|}. \quad (10)$$

Equation (9) thus becomes

$$\dot{\tilde{\mathbf{R}}} = -\mu \frac{\tau}{l_0^2} \tilde{\nabla} U(\mathbf{R}) + \tilde{\eta}(\tilde{t}). \quad (11)$$

For any configuration \mathbf{R} we define the ‘‘systemic temperature,’’ $T_s(\mathbf{R})$, by [43]

$$T_s(\mathbf{R}) \equiv \left(\frac{\partial U}{\partial S_{\text{ex}}} \right)_\rho \Big|_{S_{\text{ex}}=S_{\text{ex}}(\mathbf{R})}. \quad (12)$$

It should be emphasized that when we below use this concept in the context of active matter, that does *not* imply an implicit mapping of the active-matter system to the ordinary thermal-equilibrium system; thus no relation between the physics of the two different cases is assumed.

In a steady-state situation the fluctuations of the systemic temperature go to zero in the thermodynamic limit, just as those of $T_{\text{conf}}(\mathbf{R})$. For this reason we henceforth occasionally leave out \mathbf{R} and write simply T_s . In practice, to determine $T_s(\mathbf{R})$ one utilizes the fact that $T_s(\mathbf{R})$ is the equilibrium temperature T_{eq} of the thermodynamic state point with the density

of \mathbf{R} and potential energy equal to $U(\mathbf{R})$, implying that [43]

$$T_s(\mathbf{R}) = T_{\text{eq}}(\rho, U(\mathbf{R})). \quad (13)$$

This means that there is no need to evaluate any entropy in order to determine T_s , which is simply the temperature of the thermal-equilibrium state point with same density and potential energy as the active-matter system in question.

Equation (8) implies $\tilde{\nabla} U(\mathbf{R}) = T_s \tilde{\nabla} S_{\text{ex}}(\tilde{\mathbf{R}})$. When substituted into Eq. (11) this results in

$$\dot{\tilde{\mathbf{R}}} = -\mu \frac{\tau T_s}{l_0^2} \tilde{\nabla} S_{\text{ex}}(\tilde{\mathbf{R}}) + \tilde{\eta}(\tilde{t}). \quad (14)$$

It follows from Eq. (10) and Eq. (14) that the reduced AOUP equation of motion is invariant upon a density change if $\tau D/l_0^2$ and $\tau T_s/l_0^2$ do not vary with density. This implies $D(\rho) \propto T_s(\rho)$ and $\tau(\rho) \propto \rho^{-2/3}/T_s(\rho)$ in which $T_s(\rho)$ is short-hand notation for $T_{\text{eq}}(\rho, S_{\text{ex}}(\tilde{\mathbf{R}}))$; compare Eq. (13). Working from the reference state point (ρ_0, D_0, τ_0) , this means that the function $T_s(\rho)$ determines how to scale D and τ to ensure invariant AOUP dynamics,

$$\begin{aligned} D(\rho) &= D(\rho_0) \frac{T_s(\rho)}{T_s(\rho_0)}, \\ \tau(\rho) &= \tau(\rho_0) \left(\frac{\rho_0}{\rho} \right)^{2/3} \frac{T_s(\rho_0)}{T_s(\rho)}. \end{aligned} \quad (15)$$

We next link to the configurational temperature. There is no reason to expect $T_{\text{conf}} = T_s$ in out-of-equilibrium situations, and these quantities indeed differ by up to a factor of six in our simulations (Paper II [42] suggests using T_s/T_{conf} as a measure of the degree of deviation from thermal equilibrium). However, Eq. (15) still applies with T_{conf} instead of T_s if the two temperatures are proportional in their density variation. To show that this is the case we note that Eq. (8) implies $\tilde{\nabla} U(\mathbf{R}) = T_s \tilde{\nabla} S_{\text{ex}}(\tilde{\mathbf{R}})$ and $\tilde{\nabla}^2 U(\mathbf{R}) = T_s \tilde{\nabla}^2 S_{\text{ex}}(\tilde{\mathbf{R}})$, so $T_{\text{conf}}(\mathbf{R}) = [\nabla U(\mathbf{R})]^2 / \nabla^2 U(\mathbf{R}) = [\tilde{\nabla} U(\mathbf{R})]^2 / \tilde{\nabla}^2 U(\mathbf{R}) = T_s [\tilde{\nabla} S_{\text{ex}}(\tilde{\mathbf{R}})]^2 / \tilde{\nabla}^2 S_{\text{ex}}(\tilde{\mathbf{R}})$ [43]. Here we ignored the dependence of $T_s(\mathbf{R})$ on the configuration \mathbf{R} which, as mentioned above, vanishes in the thermodynamic limit. In terms of $\phi(\tilde{\mathbf{R}}) \equiv [\tilde{\nabla} S_{\text{ex}}(\tilde{\mathbf{R}})]^2 / \tilde{\nabla}^2 S_{\text{ex}}(\tilde{\mathbf{R}})$ we thus have

$$\frac{T_{\text{conf}}(\mathbf{R})}{T_{\text{conf}}(\mathbf{R}_0)} = \frac{T_s(\rho) \phi(\tilde{\mathbf{R}})}{T_s(\rho_0) \phi(\tilde{\mathbf{R}}_0)}. \quad (16)$$

Since $\tilde{\mathbf{R}} = \tilde{\mathbf{R}}_0$ this implies $T_{\text{conf}}(\mathbf{R})/T_{\text{conf}}(\mathbf{R}_0) = T_s(\rho)/T_s(\rho_0)$. In this way Eq. (15) leads to Eq. (4). Note that by using T_{conf} instead of T_s , one does not have to identify the equilibrium state point with the same potential energy as the active-matter state point in question. Figure 1 and Fig. 2 demonstrated good invariance along active-matter isomorphs determined by means of Eq. (4). A more accurate, but also more demanding method for determining the active-matter isomorphs of AOUP LJ systems, which utilizes T_s directly, is discussed in the Appendix.

We end this section by checking a consequence of the above. It was shown in Ref. [56] that for LJ systems, if W_0 is the virial for the state point of zero potential energy on a given isomorph, the following relation between the virial W

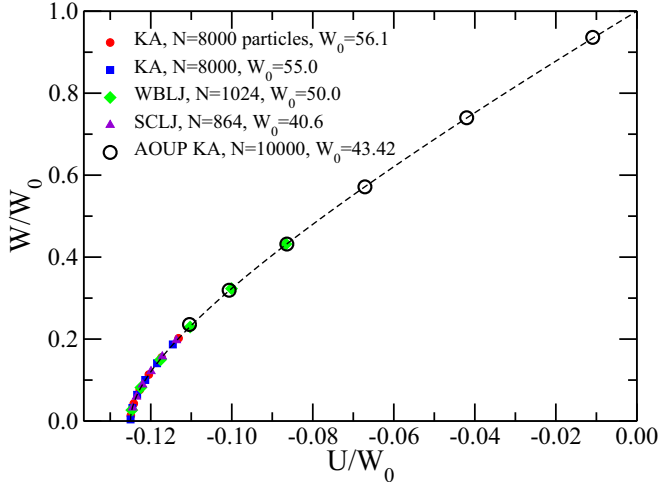


FIG. 4. “Master isomorph” [dashed curve, Eq. (17)] expressing the virial W as a function of the potential energy U along any isomorph of any type of LJ systems; W_0 is the virial at the state point of zero potential energy on the isomorph in question. The figure is Fig. 8 of Ref. [56] to which we have added data for the AOUP KA model (open circles). The abbreviations KA, WBLJ, and SCLJ represent the Kob-Andersen system, the Wahnstrom binary LJ mixture [57], and the standard single-component LJ system, respectively.

and the potential energy U applies along the isomorph

$$2 \frac{W}{W_0} = 1 + 8 \frac{U}{W_0} + \sqrt{1 + 8 \frac{U}{W_0}}. \quad (17)$$

This identity is a consequence of the reduced-unit RDF isomorph invariance, which applies in the R-simple region of any single- or multicomponent LJ system (i.e., liquid or solid, but not gas) [56]. Since the reduced RDF is also invariant to a good approximation along the above studied KA active-matter isomorph (Fig. 1), W should also in this case be determined by U according to Eq. (17). This prediction is validated in Fig. 4 that reproduces the Newtonian-dynamics equilibrium data of Ref. [56] to which our data have been added (open circles).

IV. DISCUSSION

The isomorph concept of equilibrium Newtonian dynamics was recently generalized to out-of-equilibrium Newtonian systems like that of a shear flow or an aging glass, leading to the introduction of the concept of a systemic temperature [Eq. (12)], which allows for the identification of lines of approximately invariant structure and dynamics in the relevant out-of-equilibrium phase diagram [43]. The results of the present paper extend these findings by demonstrating the existence of isomorphs for active-matter systems, which in contrast to Newtonian systems are described by a dynamics that is not time-reversible.

The configurational temperature expression is derived from the canonical ensemble. This paper has nevertheless demonstrated the relevance of T_{conf} for tracing out lines of approximately invariant physics in the phase diagram of Ornstein-Uhlenbeck active-matter models involving a potential-energy function that obeys hidden scale invariance.

We emphasize that this application is not based on a mapping of the active-matter system to an equilibrium system.

Paper II [42] demonstrates the existence of active-matter isomorphs for active Brownian particle dynamics and proposes a second application of T_{conf} to active matter: It is argued that the ratio of the systemic to the configurational temperature, which is unity in thermal equilibrium because $T = T_s = T_{\text{conf}}$, provides a simple measure of the degree of deviation from thermal equilibrium.

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APPENDIX: A MORE ACCURATE METHOD FOR TRACING OUT ACTIVE-MATTER ISOMORPHS

Equilibrium isomorphs may be traced out by different methods, e.g., step-by-step integration of the exact equation for a configurational adiabat [35,58], the direct isomorph check [35], and the recently introduced force method [59]. These are numerical methods of varying complexity and accuracy. Likewise, there are different numerical methods for tracing out an active-matter isomorph. We describe below a more accurate alternative to the method used in Secs. II and III, a method that is however also more involved.

The paper demonstrated how T_{conf} can be used for tracing out active-matter isomorphs from a single configuration of the AOUP model. The result was a recipe for calculating how model parameters are to be changed as functions of the density in order to arrive at approximately invariant structure and dynamics, Eq. (5). This recipe provides a useful “quick-and-dirty” method which, since it relies on Eq. (8), is exact whenever hidden scale invariance holds exactly [which is only the case if $U(\mathbf{R})$ is an Euler-homogeneous function]. A more accurate, but also more cumbersome, method for identifying active-matter isomorphs refers directly to the concept of systemic isomorphs. These lines in the (ρ, T_s) phase diagram are by definition the same as the ordinary isomorphs of the canonical-ensemble equilibrium (ρ, T) phase diagram [43] (ordinary, systemic, and active-matter isomorphs are all defined as lines of constant S_{ex} in the respective phase diagrams).

To test the consequence of referring directly to the systemic isomorph, we traced out the systemic isomorph of the KA system by the direct isomorph check (DIC) method [35], which

TABLE II. Ratio of the model parameters D and τ along the predicted line of invariance calculated from Eq. (5) (subscript “c”) and from the fact that the systemic isomorph corresponds to an equilibrium isomorph (subscript “s”).

ρ	D_c/D_s	τ_c/τ_s
1.2	1.000	1.000
1.5	1.139	0.878
2.0	1.278	0.782
2.5	1.345	0.743
3.0	1.382	0.723

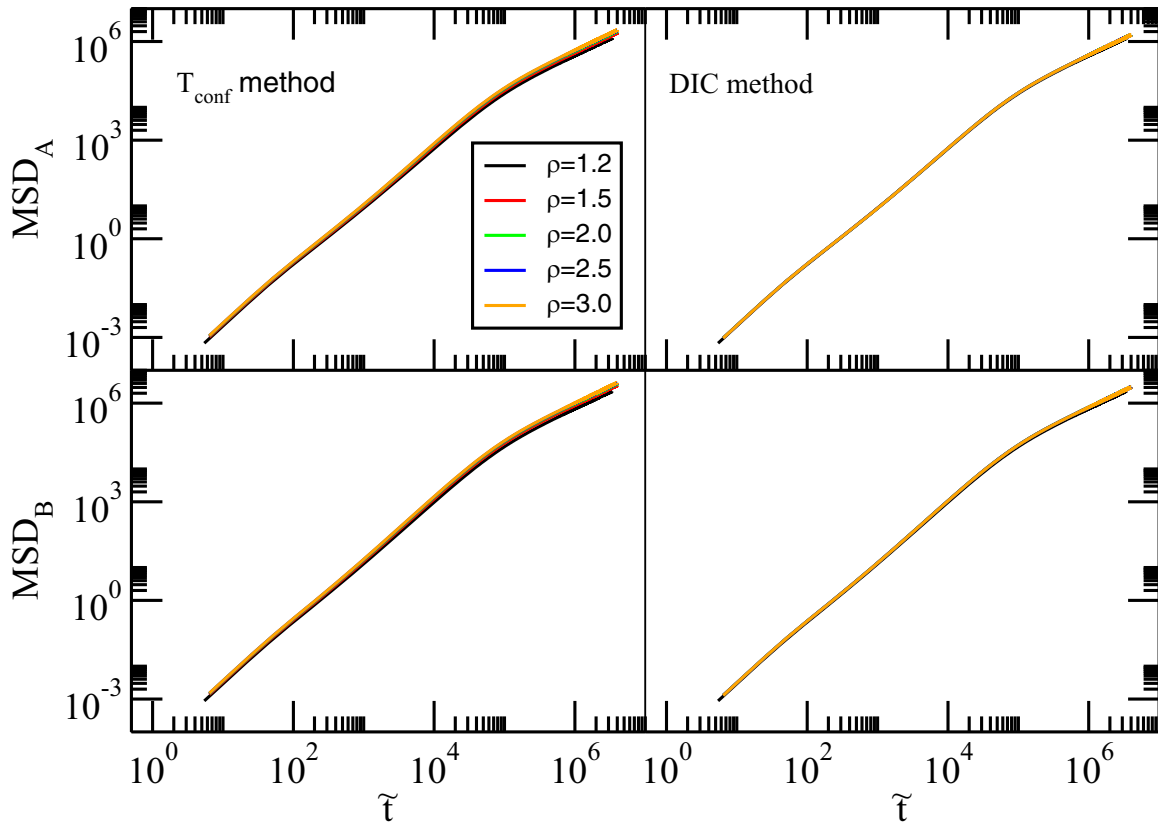


FIG. 5. Reduced MSD of the A and B particles as functions of reduced time along active-matter isomorphs of the AOUP KA model traced out by two different methods. The left column reproduces the data of Fig. 2 where the isomorph was traced out by the above-developed T_{conf} method. For comparison, the right column gives MSDs when the isomorph is traced out by the direct isomorph check (DIC) method [35] in its analytical version for LJ-type systems [60,61], which refers directly to the fact that a systemic isomorph in the (ρ, T_s) phase diagram is identical to an equilibrium isomorph in the standard (ρ, T) phase diagram. The active-matter-isomorph invariance is improved by this method.

is accurate and has a simple analytical expression for LJ-type systems [60,61]. Table II gives the ratios of the parameters predicted by the two different methods for tracing out the active-matter isomorph. It does not make a huge difference which method is used, but there is some improvement using the DIC method. This is illustrated in Fig. 5, which in the left column from Fig. 2 reproduces the reduced MSD as a function

of reduced time for the A and B particles. The right column gives similar data when the model parameters are instead determined by identifying the function $T_s(\rho)$ by utilizing the fact that this function is identical to $T(\rho)$ of the corresponding equilibrium isomorph, which may be determined by the DIC method [60]. We see that the MSD is more invariant in the latter case, confirming that this method is indeed more accurate.

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